

Q4 P1

$$\frac{dx}{dt} = -2x + \frac{1}{2}y \quad (1)$$

$$\frac{dy}{dt} = -y \quad (2)$$

$$(2) \quad \frac{dy}{dt} = -y \Rightarrow y = Ae^{-t}$$

$$\Rightarrow \frac{dx}{dt} = -2x + \frac{A}{2}e^{-t}$$

$$x' + 2x = \frac{A}{2}e^{-t} \quad | \cdot e^{2t}$$

$$(xe^{2t})' = \frac{A}{2}e^t$$

$$xe^{2t} = \frac{A}{2}e^t + B$$

$$x = \frac{A}{2}e^{-t} + Be^{-2t}$$

$$\begin{pmatrix} x \\ y \end{pmatrix} = A \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix} e^{-t} + B \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{-2t}$$

eigenvalues: $-1, -2 \rightarrow (0,0)$ origin
be a sink!

$$\text{SUS: } A \begin{pmatrix} \frac{1}{2} \\ 1 \end{pmatrix} e^{-t}$$

$$B \begin{pmatrix} 1 \\ 0 \end{pmatrix} e^{-2t}$$

2nd order DEQS

Most important examples:
Spring mass systems

$$m y'' + b y' + k y = 0$$

y ↓

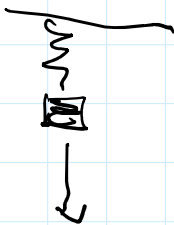


y position of the spring

m mass of the attachment to the spring

b damping factor (proportional to the velocity of the spring)

k spring constant (proportional to the stretch of the spring)



↑
Hooke's Law

$$m > 0, k > 0, b \geq 0$$

$$y'' + \frac{b}{m} y' + \frac{k}{m} y = 0$$

characteristic equation: $\lambda^2 + \frac{b}{m} \lambda + \frac{k}{m} = 0$

$$\lambda = -\frac{b}{2m} \pm \sqrt{\frac{b^2}{4m^2} - \frac{k}{m}}$$

$$\lambda = -\frac{b}{2m} \pm \sqrt{\frac{b^2 - 4mk}{4m^2}}$$

Observations: - Both eigenvalues: $\lambda \leq 0$

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$$\text{Check: } -\frac{b}{2m} - \sqrt{\dots} < 0$$

$$\frac{b^2}{4m^2} - \frac{k}{m} < \frac{b^2}{4m^2}$$

$$\text{or } \frac{b}{2m} > \sqrt{\frac{b^2}{4m^2} - \frac{k}{m}}$$

so the second eigenvalue ≤ 0
as well.

- if $b > 0$, both eigenvalues are negative

3 cases 1) $b^2 - 4mk > 0$

2 real eigenvalues, negative: λ_1, λ_2
solutions will be

$$y(t) = A e^{\lambda_1 t} + B e^{\lambda_2 t}$$

Overdamped
spring

2) $b^2 - 4mk = 0$

1 real eigenvalue repeated: λ

$$y(t) = A e^{\lambda t} + B t e^{\lambda t}$$

Critically
damped

border case

3) $b^2 - 4mk < 0$

complex eigenvalues: $\lambda = \alpha \pm i\beta$
($\alpha \leq 0$)

$$y(t) = A e^{\alpha t} \cos(\beta t) + B e^{\alpha t} \sin(\beta t)$$

normal case

Underdamped
Spring

$\underbrace{\quad \quad \quad}_{D \dots}$

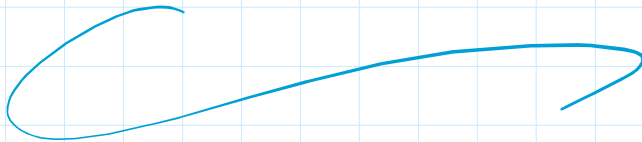
$$y(t) = A e^{-\dots} \cos(\dots) + B e^{-\dots} \sin(\dots)$$

4)

$$x = 0 \Leftrightarrow \theta = 0$$

undamped spring

$$y(t) = A \cos(\omega t) + B \sin(\omega t)$$



Trace - Determinant Plan

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix} \quad y' = A \cdot y$$

characteristic equation:

$$(\lambda - a)(\lambda - d) - bc = 0$$

$$\Leftrightarrow \lambda^2 - \underbrace{(a+d)}_{\text{trace } A} \lambda + \underbrace{(ad-bc)}_{\text{det } A} = 0$$

$$A = \begin{pmatrix} a & b \\ c & d \end{pmatrix}$$

$$\Leftrightarrow \lambda^2 - T \lambda + D = 0$$

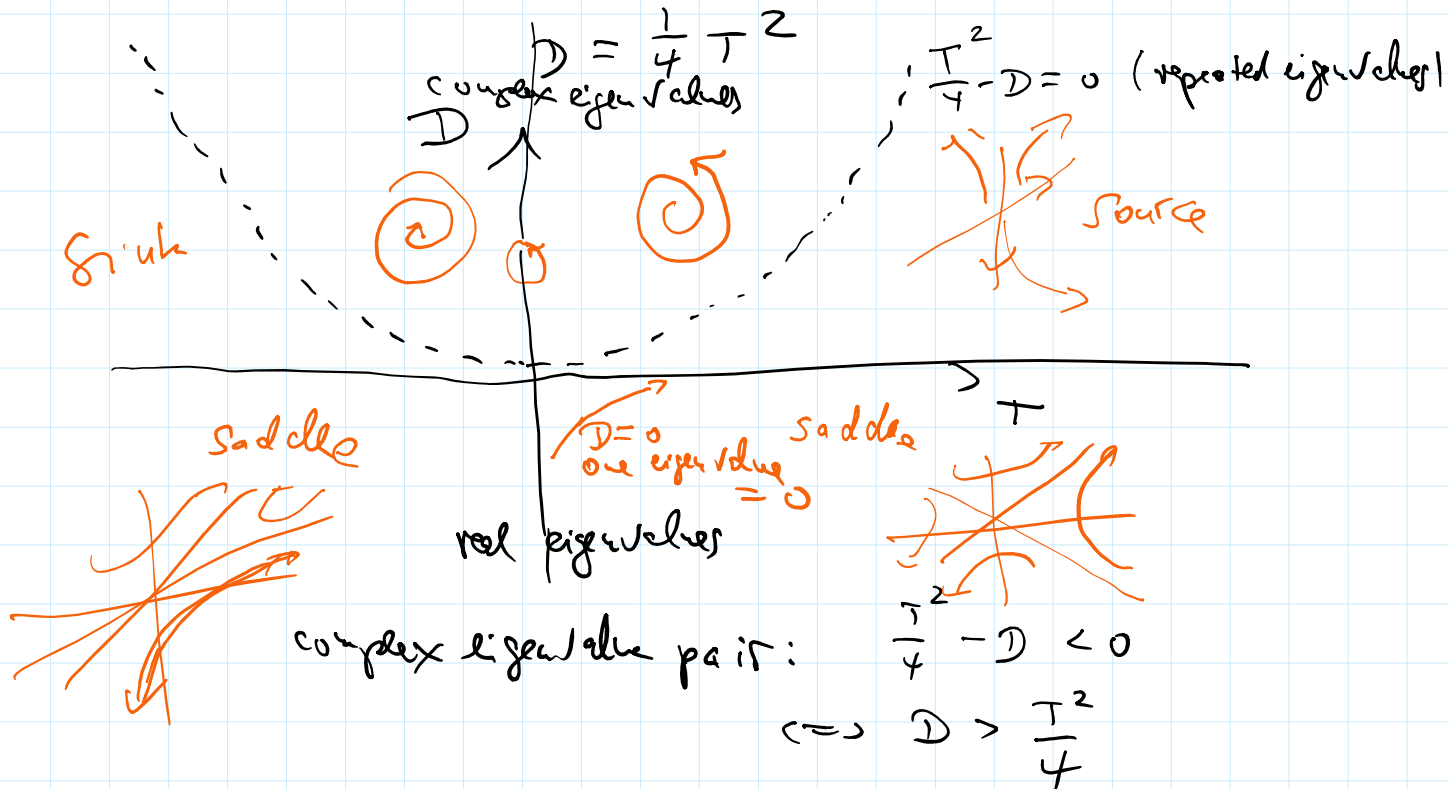
$$D = \det A = ad - bc$$

$$T = \text{tr } A = a + d$$

T & D do not determine all coefficients of A , but they determine the eigenvalues

eigenvalues: $\lambda = \frac{T}{2} \pm \sqrt{\frac{T^2}{4} - D}$

→ when is $\frac{T^2}{4} - D = 0$?



$$\lambda = \frac{T}{2} \pm \sqrt{\frac{T^2}{4} - D}$$

when $T > 0$ at least one eigenvalue > 0
 $T < 0$ at least one eigenvalue < 0

suppose $T > 0$ and $D > 0$

then the 2nd eigenvalue > 0 as well

$$D > 0 \Rightarrow \frac{T^2}{4} - D < \frac{T^2}{4}$$

$$\sqrt{\frac{T^2}{4} - D} < \frac{T}{2}$$

$$\text{so } \frac{T}{2} - \sqrt{T^2 - 4D} > 0$$

$$\text{so } \frac{T}{2} - \sqrt{\frac{T^2}{4} - D} > 0$$